Detecting, Mapping, and Grading Sidewalks using Street View Images and Secondary Sources for the city of Dallas

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**Abstract.** Sidewalks have long provided visitors and residents of municipalities with a means of accessing the resources in the area. However, for individuals with mobility challenges, the mere presence of a sidewalk is often not enough information to determine whether they are able to easily access a point of interest. Features, such as curb ramps, are often much more important in the planning of a route for the mobility challenged. In this paper, we present a neural network-based model to find and map curb ramps visible on SOME KIND OF IMAGE so that a path can be graded based on a novel qualitative scoring model called QSI (Quality of Sidewalk Index). Using a dataset DESCRIBE THE DATASET NOT WHERE YOU GOT IT FROM, we created a training set of images used to develop a convolutional neural network which identifies previously-labeled curb cuts. The model identifies the presence or absence of curb cuts 80% of the time. NEED TO SAY SOMETHING ABOUT QSI. NEED MAIN CONCLUSION.

1 Introduction

For individuals with mobility limitations, the availability of sidewalks with quality curb ramps represents a necessity in navigating a city or urban environment. In the absence of this information, wheelchair users are forced to rely on their own experience and knowledge of a specific area to successfully navigate to their destination in an efficient and safe manner. Without navigability knowledge, a wheelchair user may choose to take much longer routes, may sustain serious injuries on route without curb ramps, or may choose not to travel at all. Previous attempts at identifying curb ramps have been carried out through in-person (subjective) “Neighborhood Audits” or through information cataloged in Geographic Information Systems [NEED CITATIONS]. The completeness, timeliness, and quality of the information gathered in these methods is often lower than what is needed for a comprehensive view of the availability of navigation features, such as sidewalks and curb ramps, across a city. These manual approaches also tend to come with a very high cost of acquisition.

The city of Dallas approached SMU for assistance in developing an automated sidewalk/mobility grading system. There is a myriad of reasons for the city of Dallas to focus a portion of spending on sidewalk creation and repair. For the mobility impaired, availability of sidewalks is an essential requirement for moving about the metropolitan area. Additionally, sidewalks allow citizens to move in a safe manner around the city without the risks associated with walking in the streets amongst cars driven by ever-increasingly distracted drivers. Sidewalks also provide health benefits since they provide a means of pedestrian travel to near-home destinations for those who may otherwise choose to not travel. Additionally, sidewalks in disrepair tend to contribute to the “broken-windows” theory surrounding many under-privileged areas of the metroplex. Overall, sidewalks represent a worthwhile investment for the city and provide a means of safe and healthy travel for those who choose pedestrian transportation.

Despite the obvious benefits of accessibility to a city and its citizens, the problem of documenting and mapping current levels of accessibility is persistent. This represents an issue for the city in the proper allocation of resources to the different parts of the city. It also represents an issue for the citizens and visitors: difficulty navigating the city due to gaps in the availability of sidewalks and curb ramps for mobility impaired users.

In the fiscal year 2015, Dallas had a proposed budget for infrastructure projects, such as sidewalks, of $7,135,208 [NEED CITATION]. This budget has grown each of the past several years as the city has increased in size [NEED CITATION]. The city of Dallas has grown in both its inhabited sprawl and in the density of the population at double-digit rates over the past 5 years [NEED CITATION]. This growth can be explained by the city’s pro-business mentality and the relative value proposition that such a large city provides. Dallas boasts a centrally located position in the country, and the city’s status as a transportation hub allows businesses to send employees to any destination in the world with relative ease and efficiency. The city and state have pro-business tax and incentive policies that have encouraged this growth. With this growth, the city must acquire a better way of allocating the budget for sidewalks and other infrastructure.

Today, the city of Dallas essentially responds to complaints about sidewalks through its street services program that receives incident reports [NEED CITATION]. As incidents are received, the city generally puts each incident on a list for assessment. There is no priority granted for severity of the situation causing each incident to be treated with the same level of urgency. Additionally, maintenance in suburban areas is the responsibility of the home or property owner, and this is not necessarily considered in the ranking process. The current process takes 2-3 months in order to get an assessment and cost estimate for each incident or property owner. NEED SENTENCE SAYING WHO DOES THE ASSESSMENT. Once the assessment has been done, either the city or the property owner will plan and fund the project. One program in Dallas allows the city to reimburse homeowners up to $500 or 50% of the repair cost, whichever is less [NEED CITATION].

Under these circumstances, the city spends significant time and resources just completing the assessments. Using the neural-networks-based approach that we present in this paper, the city would be able to feed images of these incidents into the model and immediately receive a grading of the sidewalk in question. The city officials could then compare this grading to the grading of previous works to know whether this sidewalk was an immediate issue, who owns the sidewalk, and how much the repair may cost. This would allow the city to prioritize incidents into bins such as: critical, severe, moderate, and low-risk. Therefore, Dallas could dispatch crews to the areas where their services will be the most impactful to the safety and health of the public.

We present a machine learning based solution DESCRIBE WHAT THE SOLUTION DOES NOT THE PROBLEM SOLVED. Using a training set of images from Project Sidewalk at the University of Maryland, several machine learning methods were evaluated for accuracy in detecting curb cuts in a sidewalk. A method to extend the trained model to the full geography of the city of Dallas is also outlined. Additionally, we suggest an approach to leveraging this model to make sound recommendations regarding areas of focus for the city planning commission.

NEED PARAGRAPH INDICATING THE ORGANIZATION OF THE REST OF THE PAPER. The remainder of this paper is organized as follows. In Section 2 we examine related work. In Section 3 we…WAIT! THERE IS NO SECTION 3. In Section 4 we… We draw the relevant conclusions in Section Z.

2 Related Work

Image recognition using machines to recognize images began development in earnest in the early 1960’s. As early as 1963, the electrical engineering department at MIT began using computers to recognize 3D images [NEED CITATION]. While these initial applications were somewhat simple compared to those that we currently use today, they paved the way for what has now become a commonplace practice across industries.

Bahlman, Zhu, and Pelkofer’s work [3] provided meaningful advancements in image element detection and classification. The authors built upon their previous research involving shape and color recognition to help classify street signs and traffic signals. Their work utilizes a 2-step approach where if the model fails on the first classification step, the image is thrown out. This model is important to our work, because it shows how an algorithm such as Adaboost can be used to detect both anomalous and important features for an image-based problem.

Perona presents SOMETHING IN “A Bayesian Hierarchical Model for Learning Natural Scene Categories” [4]. Perona provides an approach that allows for very hands-off model building. In Perona’s model, the computer attempts to use human-based rules to classify image objects. Essentially, each image is broken down into a series of codebook images and reoccurring elements are scanned and classified. Each of these codebook images is additionally clustered using k-means clustering. This portion of the model is used to eliminate features that occur with low frequencies in the training data. The model was able to achieve a 78% accuracy rate with a low amount of supervision.

An aspect of previous work that is of high importance for our work is the use and application of convolutional neural networks. Goodfellow and a team from Google [5] showed an application of convolution neural networks for image recognition. In this work, Goodfellow applied the DistBelief method for neural networks combined with Google Streetview images to recognize multi-digit numbers, namely street addresses. In their model, Goodfellow first addressed training the model to identify house numbers. This was a very important step as many variables come into play with these image captures. For instance, lighting, obstructions, and changing conditions can provide potential issues when identifying numbers from images. Additionally, varying font sizes, colors, and styles can impact the ability of the algorithms to correctly identify an image. An important aspect of this type of recognition is that if a single digit is misidentified, the entire interpretation is irrelevant and meaningless. Once the model was trained on house numbers, a more complete Streetview dataset was used. The final approach involved subtracting the mean from each image. In the end, Goodfellow’s models were able to achieve a 97.84% accuracy with this approach, which was just short of the human benchmark of 98% that was the target of the project. BE SPECIFIC IN HOW YOU USED/STOLE/MODIFIED PORTIONS OF THIS APPROACH FOR YOUR WORK.

Convolutional neural networks have also been used to improve the solutions submitted in the ImageNet Large-Scale Visual Recognition Challenge. In the work of Simonyan, Karen, and Zisserman [6], the team used convolutional neural networks combined with several other approaches to achieve STATE THE ACCURACY LEVEL, one of the highest accuracy levels seen in the competition.

Logistic Regression and Artificial Neural Networks have become benchmarks in classification tasks across problem types. Dreiseitl and Ohno-Machado [19] researched the methodology of machine learning methods across more than 70 papers. The authors state that the two methods, Logistic Regression and Artificial Neural Networks, both have similar basis: statistical pattern recognition in large data sets. The authors reviewed 72 papers that compared outcomes of implementations of both logistic regression, and artificial neural networks. Artificial neural networks outperformed logistic regression in 51% of the studies, but 42% of the studies provided no difference in outcome between the methods. The underlying context, and understanding the authors are seeking is the ability to implement a model to a medical context. They label logistic regression and several other methods as a “White box” method, where the parameters are clearly stated and the method that the model uses to assign importance and come to a conclusion are clearer. In contrast, Artificial Neural Network and support vector machines are labeled as “black box” methods that do not provide interpretable markers of importance or provide methods to be verifiable.

The current reach of accessibility features in the urban landscape is central to the research that was performed by ????. Bennett, Kirby, and MacDonald [17] surveyed 79 intersections in Halifax, Nova Scotia. Their scoring methodology asked 8 different questions that addressed both the presence and quality of curb ramps at these intersections. Each question required a binary response. Several of the questions would appear to be answerable from the research we propose – the presence of curb ramps, accessibility from the line of travel (that is, the chair user can access the ramp without exiting the crosswalk), that the ramp is “free from irregularities”, and free from drainage grates. Four additional questions address the question of slopes and dimensions of the curb ramp. Their findings in the limited scope of the survey was that 98.7% of intersections had curb ramps, but just more than half, 53.8, had a direct line of travel from the crosswalk. All of the ramps were free from drainage grates, and 85.9% were free from irregularity. The average intersection scored 5.6. The researchers proposed that wheelchair users must adapt to the lack of infrastructure by increasing their skill and dexterity in maneuvering the chair. WHY IS THIS BAD?

Bromley *et al.* [18] noted that legislation in the United Kingdom seeks to provide access to goods and services to all persons, but not necessarily the facilities containing goods and services. It is a fine distinction between the two, and within this context it could be judged that this is the granular difference that describes how accessibility isn’t a special accommodation but provides equal access to all. Respondents in Bromley *et al*.’s survey-based study in Swansea, Wales found 60% thought that lack of curb ramps were a “major” or “prohibitive” obstacle to access. Respondents used domain knowledge of the city to navigate around obstacles, and sometimes take much longer paths to access facilities. Among the respondents, 60.8% agreed that “the way places are designed” is the major problem for wheelchair users. This attitude was more evident among younger users of wheelchairs than their older cohort. Wheelchair users recommended “more dropped kerbs” more often than any other improvement to the center city shopping experience.

Another piece of research on accessibility was Clarke *et al*’s [13] audit of Streetview images as compared with an individual’s in-person audit. The study involved researchers in neighborhoods in Chicago walking each block from the inside to the outside, essentially walking the block twice, and assessing the quality of the sidewalks. This study found that subjective measures like sidewalk quality have much lower consistency between observation via Streetview and in-person observation and grading. Essentially, the conclusion is that features requiring high levels of precision can be hard to attain via Streetview images. NO OPINIONS. For instance, our model will need to stay informed of areas that have been treated in the previous time periods. Therefore, if a database of previously updated sidewalks does not exist, we will need to provide a means of storing projects within a database that allows for those items or coordinates to be referenced. This will prevent outdated Streetview images from being used in the classification and scoring process.

While our problem can be solved via machine learning techniques, there is indeed a reason for the application of these techniques to solve the task at hand. Namely, improving sidewalk quality, coupled with other factors, can lead to better health for society overall. In Haina et al [11], the researchers looked at signal data such as walkability of neighborhoods in relation to the overall health of the individuals in the area. The evidence used to provide insight into the improved environment of an area was sanitation practices and tobacco sales restriction. This coupled with increased walkability of an area leads to higher levels of physical activity and better health over time.

Deehr and Shumann [7] provided work?????? for five different neighborhoods in the Seattle area. Their research considered the incidence of pedestrian strikes by motorists, the health factors of walking, and the current modes of transportation that pedestrians were using. Their research led to the city adding additional walking paths, and trails. Additionally, much of the research sparked additional community involvement in the design of multi-model transportation infrastructure.

In Richardson *et al* [10], the authors sought to understand whether factors such as green space and walkability resulted in “moderate to vigorous physical activity” for the residents of randomly selected neighborhoods in Pittsburg, PA. When controlling for factors such as crime, green space, and walkability in the selected targets, it was discovered that variables such as gender, age, education, and overall walkability of the neighborhood did play significant roles in the levels of physical activity for an area. This research reaffirms that there is potential for identifying areas that need accessible infrastructure.

3 Convolution Neural Networks

NEED A SECTION ON CONVOLUTION NEURAL NETWORKS.

4 Algorithm Design

NEED MORE DETAILS. LIKELY THIS SHOULD BE MULTIPLE SECTIONS SINCE YOU HAVE MULITPLE ASPECTS TO THE WORK – NEURAL NET IS DIFFERENT FROM QSI MODEL ETC. EACH PART NEEDS MORE DETAILS.

The approach selected implemented a convolutional neural network. The model employs a simple 4-layer approach and the implementation of relu as the activation function with the popular and efficient Adam optimization algorithm. In the interest of processing time, the images received from the Google StreetView were rescaled to 100 by 100 pixels with the color vector retained in the image. Each image was also scaled prior to being fed into the model. While there are many means for strong cross-validation procedures in existence, the chosen approach in this instance was a simple 80/20 split. This provided the model with plenty of data from which to learn and a modest amount of data for testing. Additionally, the model used the Keras sequential model with Google’s TensorFlow backend. The model also used 30 filters for each image and the size of each scanning filter was 3 by 3. This approach, while standard proved to be fairly robust and prevented the model from over-learning. Additionally, max pooling was also employed as a measure of overfitting, and a pool size of 2 by 2 was used. In order to test the ability of the model to improve upon its accuracy, a GridSearch of the filter parameter was performed. Upon further evaluation, of the filters, it was ultimately decided that 30 filters was optimal. Since adding additional filters did not tend to increase accuracy, and greatly increased compute time, it was decided that the 30-filter approach was indeed a sound model parameter.

The resulting model identifies curb cuts correctly 80% of the time. As a baseline approach, a Support Vector Machine and a Logistic Regression were both trained on the same data and evaluated for accuracy. Both models only resulted in an accuracy score of 67%. Therefore, the Convolutional Neural Network did indeed provide a level of precision that could not be attained in more basic machine learning approaches. It was also noticed that the time needed to train these models was also considerably more than the amount of time needed to train the neural network.

The output of this approach leads to the implementation of the QSI model that can then be used for municipalities to identify areas of focus for accessibility investment. The QSI is simple. The score is essentially just the number of curb ramps divided by the number of intersections for each 1 mile of street. It is recommended that streets be broken into 1-mile blocks for assessment purposes. This ensures that city grids do not become diluted in the overall assessment of the city streets. (NEXT STEPS)

Currently, we are working on a way to ingest images of 1-mile street blocks from areas of Dallas in order to score those streets with our model. We will then be able to rank 1-mile street sections for Dallas, see how Dallas compares to other major metropolitan areas, and recommend areas for attention to the city planning committee. This recommendation will be the ultimate output of our presentation

NEED RESULTS SECTION SEPARATE FROM THE ALGORITHM DESCRIPTION – RESULTS SHOULD BE PRESENTED IN TABLES/FIGURES

NEED ANALYSIS SECTION OF YOUR RESULTS

5 Ethics

NEED CONCLUSIONS SECTION

6 Github

The address for this work’s Github page is: [github.com/dpmurraygt/CapstoneProject](file:///C:\SMU%20Data%20science\capstone\AppData\Local\Temp\Temp1_CapstoneProject-master.zip\CapstoneProject-master\github.com\dpmurraygt\CapstoneProject)

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